

PAC-5070 User Guide

Introduction:

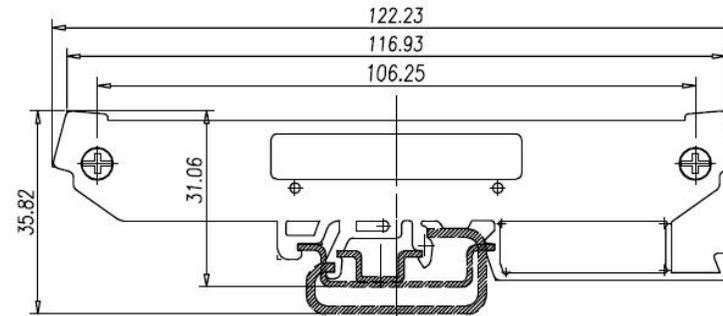
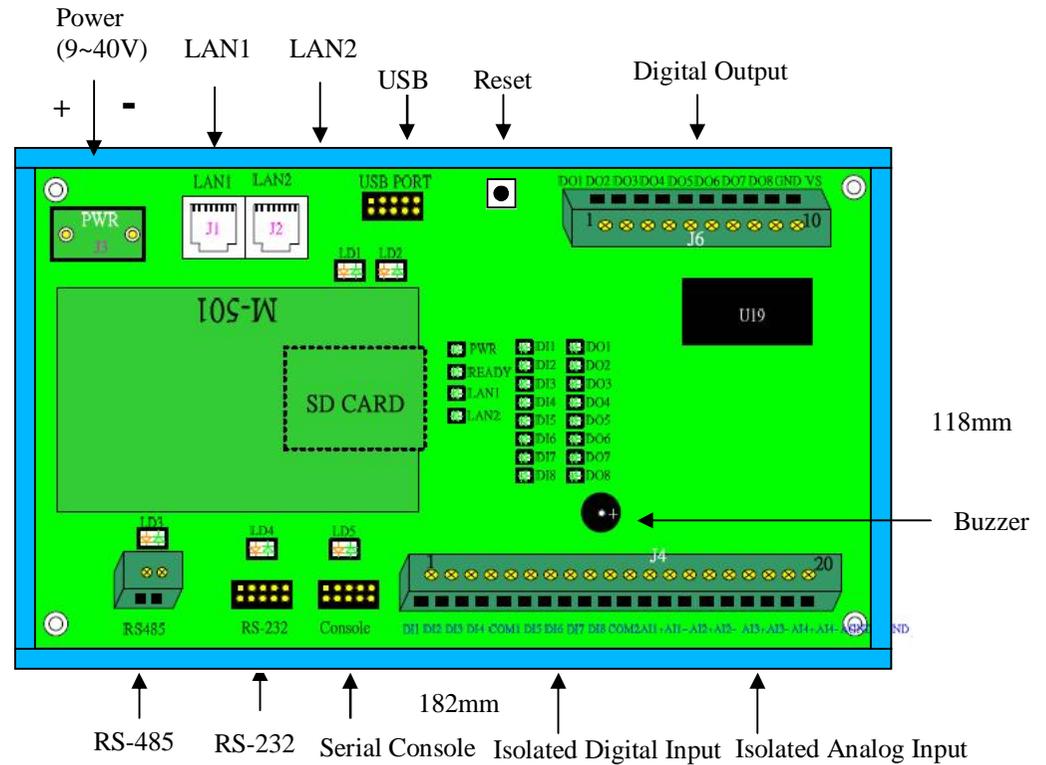
PAC-5070 is ARM9-based Linux ready industrial Programmable Automation Controller. The key features are as follow:

1. ARM920T ARM Thumb Processor with 200MIPS at 180MHz, Memory Management Unit
2. 16-KByte Data Cache and 16-KByte Instruction Cache
3. 64MB SDRAM, 16MB Flash on board
4. Two 10/100 Mbps Ethernet
5. Two USB 2.0 full speed (12 Mbps) Host Ports
6. Multimedia Card Interface for SD memory card
7. One RS-485, One RS-232 and One serial console port
8. 4 isolated analog inputs
9. Input type: mV, V, mA
10. Input range: +/- 150mV, +/- 500mV, +/- 1V, +/- 5V, +/- 10V, 0~150mV, 0~500mV, 0~1V, 0~5V, 0~10V, 0~20mA
11. 1500 Vdc isolation
12. 8 opto-isolated digital inputs
13. 8 Darlington-pair digital outputs
14. 9 to 40VDC power input
15. Pre-installed Standard Linux 2.6 OS
16. GNU tool chain available in Artilla CD
17. DIN RAIL mounting

Packing List

1. PAC-5070
2. CBL-F10M9-20: 10-pin header to DB9 male cable for RS-232 x1
3. Artilla CD

PAC-5070 Layout



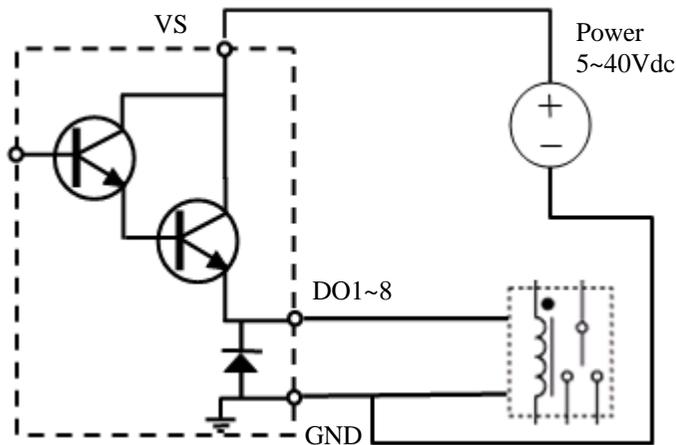
Power Input Connector (J3)

PAC-5070 uses +9VDC to 40VDC power and input from J3 connector. Auto-polarity and surge protection are included in power input circuitry of PAC-5070 to provide power protection to PAC-5070.



Digital Output Connector

The digital output are equipped with 8 darlington pair transistors (Allegro UDN2981A) to switch the external relay or solenoid. The internal transient-suppression diodes permit the drive to be used with inductive load. The source voltage of the drive is from 5Vdc to 40 Vdc and the maximum driving current is 500 mA.

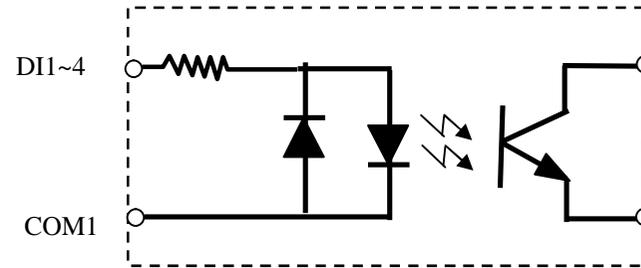


DOx: Voltage output channels
GND: Ground
VS: Voltage source input

Digital Input Connector

The 8 channel isolated input are equipped with 2500 Vrms photo coupler isolator. Four of the channels form a group and share the same common ground. The specification of the isolated input channels are:

Logical High: 5~24Vdc
Logical Low: 0~1.5Vdc
Input resistance: 1.2KOhms @0.5W
Response time: 20us
Isolation: 2500Vrms



DIx: Isolated digital input channels
COMx: common ground of four DIx

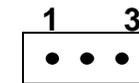
Analog Input Connector

Each of the 4 channels isolated analog input can be configured as various input range and the common features are show as follow:

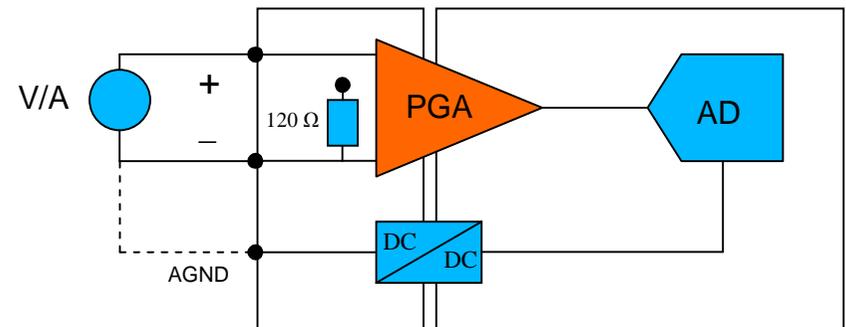
Effective Resolution: 16-bit
Channels: four differential input channels
Input Type: mV, V, mA
Input Range:
Uni-polar: 0~150mV, 0~500mV, 0~1V, 0~5V, 0~10V
Bi-polar: +/- 150mV, +/- 500mV, +/- 1V, +/- 5V, +/- 10V
Current: 0~20mA
Sampling rate: 10~100 samples /sec
Input Impedance: 20 M Ohm
Accuracy: +/- 0.1%
CMR: 50/60 Hz 100dB
Isolation: 1500Vrms (Three-way)

Each of the analog input channel provides (+) (-) and AGND input. To measure floating source such as battery (+,-) and single-ended output which provides positive (+) and ground signal, please connect the negative or ground of the signal to AGND pin in order to provide a virtual ground reference. To measure current input, please set the jumper (JP1~JP4) to current setting as show below:

Input Type Selection Jumper JP1~JP3



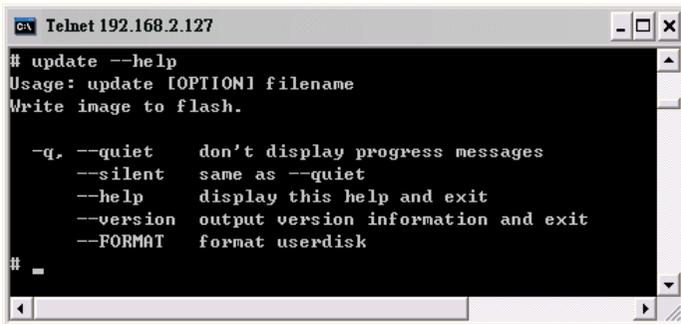
Voltage Input: 1-2 (default)
Current Input: 2-3



Artila Utility Software:

The introduction of Artila utility software as follow:

1. *update* : update loader, kernel or root file system image. Also use *update* —*FORMAT* to format user disk. Type *update—help* to find the command usage



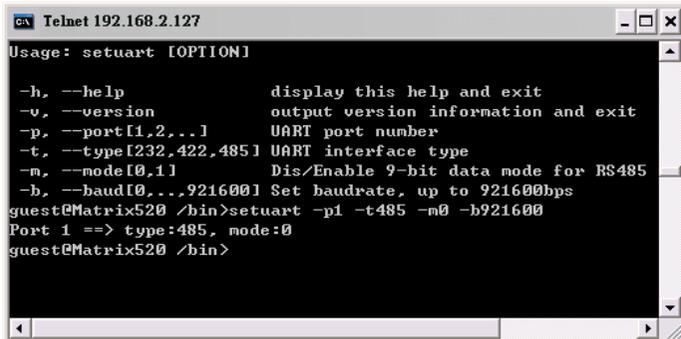
```

Telnet 192.168.2.127
# update --help
Usage: update [OPTION] filename
Write image to flash.

-q, --quiet      don't display progress messages
--silent        same as --quiet
--help          display this help and exit
--version       output version information and exit
--FORMAT        format userdisk
#
```

Update can only operated under supervisor mode (password : root)

2. *setuart*: configure serial port setting. An example show as followed to configure port 1 as RS-485 interface with baud rate 921600. Please note only port 1 support 9-bit data at RS-485



```

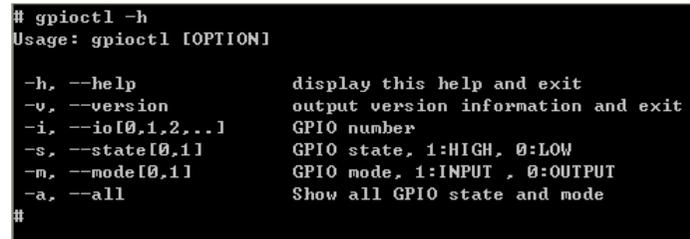
Telnet 192.168.2.127
Usage: setuart [OPTION]

-h, --help          display this help and exit
-v, --version       output version information and exit
-p, --port[1,2,..] UARTI port number
-t, --type[232,422,485] UART interface type
-m, --mode[0,1]     Dis/Enable 9-bit data mode for RS485
-b, --baud[0,..,921600] Set baudrate, up to 921600bps
guest@Matrix520 /bin>setuart -p1 -t485 -m0 -b921600
Port 1 ==> type:485, mode:0
guest@Matrix520 /bin>
```

3. *gpioctl*: gpioctl can use to control the digital input and output of PAC-5070. Use

```
>gpioctl --help
```

To find out the usage of this command.



```

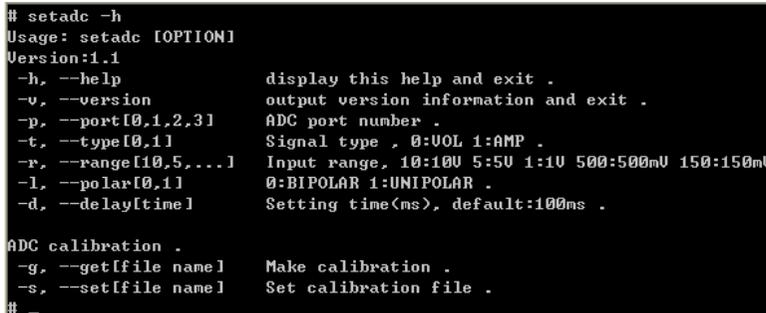
# gpioctl -h
Usage: gpioctl [OPTION]

-h, --help          display this help and exit
-v, --version       output version information and exit
-i, --io[0,1,2,..] GPIO number
-s, --state[0,1]   GPIO state, 1:HIGH, 0:LOW
-m, --mode[0,1]    GPIO mode, 1:INPUT , 0:OUTPUT
-a, --all           Show all GPIO state and mode
#
```

4. *setadc*: setadc is used to configure the analog input channels.

```
>setadc -h
```

To find out the usage of this command.



```

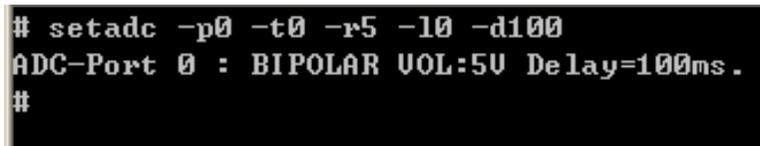
# setadc -h
Usage: setadc [OPTION]
Version:1.1

-h, --help          display this help and exit .
-v, --version       output version information and exit .
-p, --port[0,1,2,3] ADC port number .
-t, --type[0,1]     Signal type , 0:UOL 1:AMP .
-r, --range[10,5,..] Input range, 10:10V 5:5V 1:1U 500:500mV 150:150mV
-l, --polar[0,1]    0:BIPOLAR 1:UNIPOLAR .
-d, --delay[time]  Setting time(ms), default:100ms .

ADC calibration .
-g, --get[file name] Make calibration .
-s, --set[file name] Set calibration file .
#
```

To configure channel one (A11) with +/- 5V with 10 samples / sec sampling rate simply type

```
>setadc -p0 -t0 -r5 -l0 -d100
```



```

# setadc -p0 -t0 -r5 -l0 -d100
ADC-Port 0 : BIPOLAR UOL:5V Delay=100ms.
#
```

How to read Analog Input data

To read the analog data of the input channel, please follow the steps below:

1. Set the configuration of the analog channels [adc0~adc3]
2. Repeatedly read data from the device [adc0~adc3]

Note: Please set the delay time to be 100ms or longer if you want to perform multiple channels scan. The ADC device driver will delay 100 ms for Multiplexer and Programmable Gain Amplifier to be stable before taking the data from ADC.

How to make more utility software

You might also find utility software available on Artila CD under /Matrix 5XX/utility such as *ntpcient*, *ssh*, *scp*, *bluez* and *ssh-keygen*. If you want, you can ftp or copy the utility software to PAC-5070 user disk (/disk). Also you can use find the source code and use the GNU Tool Chain to make the utility by yourself.

Restore to default setting

The factory default setting is available at /default directory. Copy files in this folder to /disk will restore PAC-5070 to factory default setting.

